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A STATISTICAL SEMANTICS FOR CAUSATION

**Judea Pearl
Thomas Verma**

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Judea Pearl

TS Verma[†]

< *judea@cs.ucla.edu* > < *verma@cs.ucla.edu* >

Cognitive Systems Laboratory, Computer Science Department
University of California, Los Angeles, CA 90024

Abstract

We propose a model-theoretic definition of causation, and show that, contrary to common folklore, genuine causal influences can be distinguished from spurious covariations following standard norms of inductive reasoning. We also establish a complete characterization of the conditions under which such a distinction is possible. Finally, we provide a proof-theoretical procedure for inductive causation and show that, for a large class of data and structures, effective algorithms exist that uncover the direction of causal influences as defined above.

1 The Model

We view the task of causal modeling as an identification game which scientists play against Nature. Nature possesses stable causal mechanisms which, on a microscopic level are deterministic functional relationships between variables, some of which are unobservable. These mechanisms are organized in the form of an acyclic schema which the scientist attempts to identify.

Definition 1 *A causal model over a set of variables U is a directed acyclic graph (dag) D , the nodes of which denote variables, and the links denote direct binary causal influences.*

The causal model serves as a blue print for forming a “causal theory” – a precise specification of how each variable is influenced by its parents in the dag. Here we assume that Nature is at liberty to impose arbitrary functional relationships between each effect and its causes and then to weaken these relationships by introducing arbitrary (yet mutually independent) disturbances. These disturbances reflect “hidden” or unmeasurable conditions and exceptions which Nature chooses to govern by some undisclosed probability function.

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Definition 2 A causal theory is a pair $T = \langle D, \Theta_D \rangle$ containing a causal model D and a set of parameters Θ_D compatible with D . Θ_D assigns a function $x_i = f_i[\text{pa}(x_i), \epsilon_i]$ and a probability measure g_i , to each $x_i \in U$, where $\text{pa}(x_i)$ are the parents of x_i in D and each ϵ_i is a random disturbance distributed according to g_i , independently of the other ϵ 's and of $\{x_j\}_{j=1}^{i-1}$.

The requirement of independence renders the disturbances “local” to each family; disturbances that influence several families simultaneously will be treated explicitly as “latent” variables (see Definition 3).

Once a causal theory T is formed, it defines a joint probability distribution $P(T)$ over the variables in the system, and this distribution reflects some features of the causal model (e.g., each variable must be independent of its grandparents, given the values of its parents). Nature then permits the scientist to inspect a select subset O of “observed” variables, and to ask questions about the probability distribution over the observables, but hides the underlying causal theory as well as the structure of the causal model. We investigate the feasibility of recovering the topology of the dag from features of the probability distribution.¹

2 Model preferences (Occam’s razor)

In principle, with no restriction on the type of models considered, the scientist is unable to make any meaningful assertions about the structure of the underlying model. For example, he/she can never rule out the possibility that the underlying model is a complete (acyclic) graph; a structure that, with the right choice of parameters can *mimic* (see Definition 4) the behavior of any other model, regardless of the variable ordering. However, following the standard method of scientific induction, it is reasonable to rule out any model for which we find a simpler, *less expressive* model, equally consistent with the data (see Definition 6). Models that survive this selection are called “minimal models” and with this notion, we construct our definition of *inductive causation*:

“A variable X is said to have a direct causal influence on a variable Y if a uni-directed edge exists in all minimal models consistent with the data”

Definition 3 A latent structure is a pair $L = \langle D, O \rangle$ containing a causal model D over U and a set $O \subseteq U$ of observable variables.

Definition 4 $L = \langle D, O \rangle$ is preferred to $L' = \langle D', O \rangle$ written, $L \preceq L'$ iff D' can mimic D over O , i.e. for every Θ_D there exists a $\Theta_{D'}$, s.t. $P_{[O]}(\langle D', \Theta_{D'} \rangle) = P_{[O]}(\langle D, \Theta_D \rangle)$. Two latent structures are equivalent, written $L' \equiv L$, iff $L \preceq L'$ and $L \succeq L'$.

¹This formulation employs several idealizations of the actual task of scientific discovery. It assumes, for example, that the scientist obtains the distribution directly, rather than events sampled from the distribution. This assumption is justified when a large sample is available, sufficient to reveal all the dependencies embedded in the distribution. Additionally, we assume that the observed variables actually appear in the original causal theory and are not some aggregate thereof. Aggregation might result in feedback loops which we do not discuss in this paper. Our theory also takes variables as the primitive entities in the language, not events which permits us to include “enabling” and “preventing” relationships as part of the mechanism.

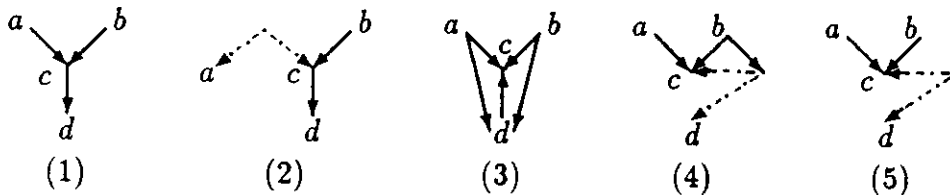
Definition 5 A latent structure L is **minimal** with respect to a class \mathcal{L} of latent structures iff for every $L' \in \mathcal{L}$, $L \equiv L'$ whenever $L' \preceq L$.

Definition 6 $L = \langle D, O \rangle$ is **consistent** with a sampled distribution \hat{P} over O if D can accommodate some theory that generates \hat{P} , i.e. there exists a Θ_D s.t. $P_{[O]}(\langle D, \Theta_D \rangle) = \hat{P}$

Definition 7 (Induced Causation) Given \hat{P} , a variable C has a **direct causal influence** on E iff a link $C \rightarrow E$ exists in every minimal latent structure consistent with \hat{P} .

We view this definition as normative, because it is based on one of the least disputed norms of scientific investigation: Occam’s razor in its semantical casting. However, as with any scientific inquiry, we make no claims that this definition is guaranteed to always identify stable physical mechanisms in nature; it identifies the only mechanisms we can plausibly induce from non-experimental data.

As an example of a causal relation that is identified by the definition above, imagine that observations taken over four variables $\{a, b, c, d\}$ reveal only two vanishing dependencies: “ a is independent of b ” and “ d is independent of $\{a, b\}$ given c ” (plus those that logically follow from the two). This dependence pattern would be typical for example, of the following variables: $a = \text{having cold}$, $b = \text{having hay-fever}$, $c = \text{having to sneeze}$, $d = \text{having to wipe ones nose}$. It is not hard to show that any model which explains the dependence between c and d by an arrow from d to c , or by a hidden common cause between the two, cannot be minimal, because any such model would be able to out-mimic the one shown in figure (1) below. We conclude therefore that the observed dependencies imply a direct causal influence from c to d . Some minimal (1 and 2) and non-minimal (3 and 4) models consistent with the observations are shown below. However, (5) is inconsistent, because it cannot account for the observed marginal dependence between b and d .



3 Proof Theory

It turns out that while the minimality principle is sufficient for forming a normative and operational theory of causation, it does not guarantee that the search through the vast space of minimal models would be computationally practical. If Nature truly conspires to conceal the structure of the underlying model she could annotate that model with a distribution that matches many minimal models, having totally disparate structures. To facilitate an effective proof theory, we rule out such eventualities, and impose a restriction on the distribution called “stability”. It conveys the assumption that all vanishing dependencies are structural, not formed by incidental equalities of numerical parameters.²

²It is possible to show that, if the parameters are chosen at random from any reasonable distribution, then any unstable distribution has measure zero [Spirtes, Glymour & Scheines 89]. Stability precludes deterministic constraints.

Definition 8 Let $I(P)$ denote the set of all conditional independence relationships embodied in P . A causal theory $T = \langle D, \Theta_D \rangle$ generates a stable distribution iff it contains no extraneous independences, i.e. $I(P(\langle D, \Theta_D \rangle)) \subseteq I(P(\langle D, \Theta'_D \rangle))$ for any set of parameters Θ'_D .

With the added assumption of stability, every distribution has a unique causal model (up to equivalence), as long as there are no hidden variables. The search for the minimal model then boils down to recovering the structure of the underlying dag from probabilistic dependencies that perfectly reflect this structure (see [Verma & Pearl 88] for a characterization of these dependencies). This search is exponential in general, but simplifies significantly when the underlying structure is sparse (see [Verma & Pearl 90] and [Spirtes and Glymour, 1991] for such algorithms).

4 Recovering Latent Structures

When Nature decides to “hide” some variables, the observed distribution \hat{P} ^{need} ~~may~~ no longer be stable relative to the observable set O , i.e. \hat{P} may result from many equivalent minimal latent structures, each containing any number of hidden variables. Fortunately, rather than having to search through this unbounded space of latent structures, it turns out that for every latent structure L , there is an equivalent latent structure called the projection of L on O in which every unobserved node is a root node with exactly two observed children.

Definition 9 A latent structure $L_{[O]} = \langle D_{[O]}, O \rangle$ is a projection of L iff (1) $L_{[O]} \equiv L$ and (2) every unobservable variable of $D_{[O]}$ is a parentless common cause of exactly two non-adjacent observable variables.

Theorem 1 Any latent structure has at least one projection (identifiable in linear time).

This result renders our definition of induced causation (Definition 7) operational; the existence of $C \rightarrow E$ need only be ascertained in a finite number of projection-like structures, each having at most $|O|^2/2$ “hidden” variables.

It is convenient to represent projections by bi-directional graph with only the observed variables as vertices (i.e., leaving the hidden variables implicit). Each bi-directed link in such a graph represents a common hidden cause of the variables corresponding to the link’s end points.

Consider the set of bi-directed graphs corresponding to the projections of all minimal latent structures consistent with an observed distribution \hat{P} . If we identify the arrowheads that are shared by all these bi-directed graphs, we obtain the sum total of all causal statements that logically follow from \hat{P} . Remarkably, these arrowheads can be identified by a simple procedure, the IC-algorithm, that is not more complex than that which recovers the unique minimal model in the case of fully observable structures.

IC Algorithm (Inductive Causation)

Input: \hat{P} a sampled distribution.

Output: $\text{core}(\hat{P})$ a marked hybrid acyclic graph.

1. For each pair of variables a and b , search for a set S_{ab} such that (a, S_{ab}, b) is in $I(\hat{P})$, namely a and b are independent in \hat{P} , conditioned on S_{ab} . If there is no such S_{ab} , place an undirected link between the variables.
2. For each pair of non-adjacent variables a and b with a common neighbor c , check if $c \in S_{ab}$. If it is, then continue. If it is not, then add arrowheads pointing at c , (i.e. $a \rightarrow c \leftarrow b$).
3. Form $\text{core}(\hat{P})$ by recursively adding arrowheads according to the following two rules:³
 If \overline{ab} and there is a strictly directed path from a to b then add an arrowhead at b .
 If a and b are not adjacent but \overline{ac} and $c - b$, then direct the link $c \rightarrow b$.
4. Mark any uni-directed link $a \rightarrow b$ if there is some link with an arrowhead directed at a .

The result of this procedure is a substructure called $\text{core}(\hat{P})$ in which every marked uni-directed arrow $X \rightarrow Y$ stands for the statement: “ X is a direct cause of Y (in all minimal latent structures consistent with the data)”. We call these relationships “genuine” causes (e.g. $c \rightarrow d$ in previous figure).

Definition 10 For any latent structure L , $\text{core}(L)$ is defined as the hybrid graph⁴ satisfying (1) two nodes are adjacent in $\text{core}(L)$ iff they are adjacent or they have a common unobserved cause in every projection of L , and (2) a link between a and b has an arrowhead pointing at b iff $a \rightarrow b$ or a and b have a common unobserved cause in every projection of L .

Theorem 2 For any latent structure $L = \langle D, O \rangle$ and an associated theory $T = \langle D, \Theta_D \rangle$ if $P(T)$ is stable then $\text{core}(L) = \text{core}(P_{[O]}(T))$.

Corollary 1 If $C \rightarrow E$ is marked in $\text{core}(\hat{P})$ then C is a direct cause of E according to \hat{P} .

5 Summary and Intuition

For the sake of completeness we now present explicit definitions of potential and genuine causation, as they emerge from Theorem 2 and the IC-algorithm.

Definition 11 (Potential Cause) A variable a has a potential causal influence on c (induced by \hat{P}), if

1. a and c are dependent in \hat{P} given some context S .

³ \overline{ab} denotes adjacency, i.e. $a - b$, $a \rightarrow b$, $a \leftarrow b$ or $a \leftrightarrow b$; \overrightarrow{ab} denotes either $a \rightarrow b$ or $a \leftarrow b$.

⁴In a hybrid graph links may be undirected, uni-directed or bi-directed.

2. There exists a third variable b such that

(i) a and b are independent in \hat{P} conditioned on S and

(ii) b and c are dependent in \hat{P} conditioned on S .

Definition 12 (Genuine Cause) A variable X has a genuine causal influence on Y if;
2. there exists a third variable Z satisfying: \leftarrow

1. X is a potential cause of Y , and

2.1. Z is a potential cause of X

2.2. Z and Y are dependent in \hat{P} given some context S .

2.3. Z and Y are independent in \hat{P} , given $S \cup X$.

Definition 11 was formulated in [Pearl 90] as a relation between events (rather than variables) with the added condition $P(Y|X) > P(Y)$ in the spirit of [Suppes 70]. Condition (1) in Definition 12 may be established either by statistical methods (per Definition 11) or by other sources of information e.g., experimental studies or temporal succession (i.e. that Z precedes X in time). When temporal information is available, as it is assumed in the formulations of [Suppes 70], [Granger, 1987] and [Spohn, 1983], then every link constructed in step 1 of the IC-algorithm corresponds to a potential cause (genuine or *spurious cause* in Suppes terminology). In such cases, Definition 12 can be used to distinguish genuine from spurious causes without requiring that all causally relevant background factors be measurable.

The intuition behind our definitions (and the IC-recovery procedure) is rooted in Reichenbach's (1956) "common cause" principle stating that if two events are correlated, but one does not cause the other, then there must be causal explanation to both of them, an explanation that renders them conditionally independent. As it turns out the pattern that provides us with information about causal directionality is not the "common cause" but rather the "common effect". The argument goes as follows: If we create conditions (fixing S_{ab}) where two variables, a and b , are each correlated with a third variable c but are independent of each other, then the third variable cannot act as a cause of a or b ; it must be either their common effect, $a \rightarrow c \leftarrow b$, or be associated with a and b via common causes, forming a pattern such as $a \leftrightarrow c \leftrightarrow b$. This is indeed the eventuality that permits our algorithm to begin orienting edges in the graph (step 2), and assign arrowheads pointing at c . Another explanation of this principle appeals to the perception of "voluntary control" [Pearl 88, page 396]. The reason people insist that the rain causes the grass to become wet, and not the other way around, is that they can find other means of getting the grass wet, totally independent of the rain. Transferred to our chain $a - c - b$, we can preclude c from being a cause of a if we find another means (b) of potentially controlling c without affecting a .

The notion of genuine causation also rests on the "common effect" principle: Two causal events do not become dependent simply by virtue of predicting a common effect. Thus, a series of spurious associations, each resulting from a separate common cause, is not transitive; it predicts independence between the first and last variables in the chain. For example, if I hear my sprinklers turn on, it suggests that my grass is wet, but not that the parking lot

at the local supermarket is wet even though the latter two events are highly correlated by virtue of a common cause in the form of rain.⁵ Therefore, if correlation is measured between my sprinkler and the wetness of the parking lot then there ought to be a non-spurious causal connection between the wetness of my grass and that of the parking lot (such as the water saturating my lawn, running off into the gutter and into the parking lot).

6 Conclusions

The results presented in this paper dispel the claim that statistical analysis can never distinguish genuine causation from spurious covariation [Otte 81], [Gardenfors, 1988]. We show that certain patterns of dependencies dictate a direct causal relationship between variables, one that cannot be attributed to hidden causes lest we violate one of the basic maxims of scientific methodology: the semantical version of Occam's razor.

On the practical side, we have shown that the assumption of model minimality, together with that of "stability" (no accidental independencies) lead to an effective algorithm of recovering causal structures, transparent as well as latent. Simulation studies conducted at our laboratory show that networks containing twenty variables require less than 5000 samples to have their structure recovered by the algorithm. Another result of practical importance is the following: Given a proposed causal theory of some phenomenon, our algorithm can identify in linear time those causal relationships that could potentially be substantiated by observational studies, and those whose directionality can only be determined by controlled, manipulative experiments.

From a methodological viewpoint, our results should settle some of the on going disputes between the descriptive and structural approaches to theory formation [Freedman 87]. It shows that the methodology governing path-analytic techniques is legitimate, faithfully adhering to the traditional norms of scientific investigation. At the same time our results also explicate the assumptions upon which these techniques are based, and the conditions that must be fulfilled before claims made by these techniques can be accepted.

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⁵apparently this lack of transitivity has not been utilized by path analysts.

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